

# Study of the effect of Regularization Errors on the developpement of Multiphase Fluid Instabilities

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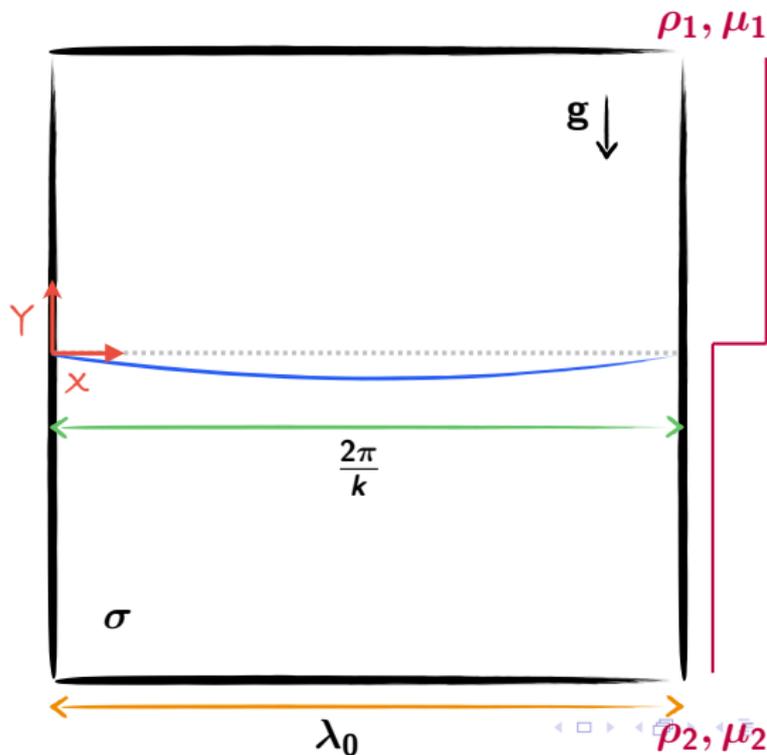
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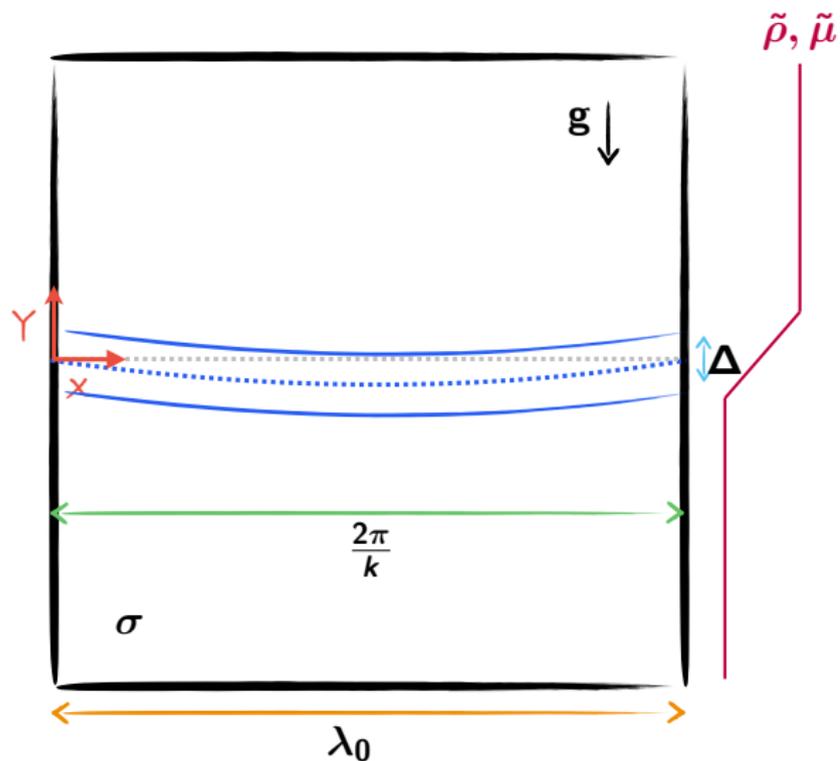


# Theoretical Setup : Classical Sharp Case

- ▶ Interfacial instability
- ▶  $\rho_1 > \rho_2$
- ▶  $g = \text{Cste}$
- ▶ Incompressible flow



# Theoretical Setup : Diffuse Case



# Simulation of the Classical One Fluid Model

- ▶ Volume of Fluid Method

$$N = \frac{\lambda_0}{\Delta_x}$$

- ▶  $\Delta = \Delta_x$

- ▶ Density Ratio  $R = \frac{\rho_2}{\rho_1} = 0.7$

- ▶ Sinusoidal Perturbation of the interface :  $h = 10^{-3} \cos(2\pi x)$

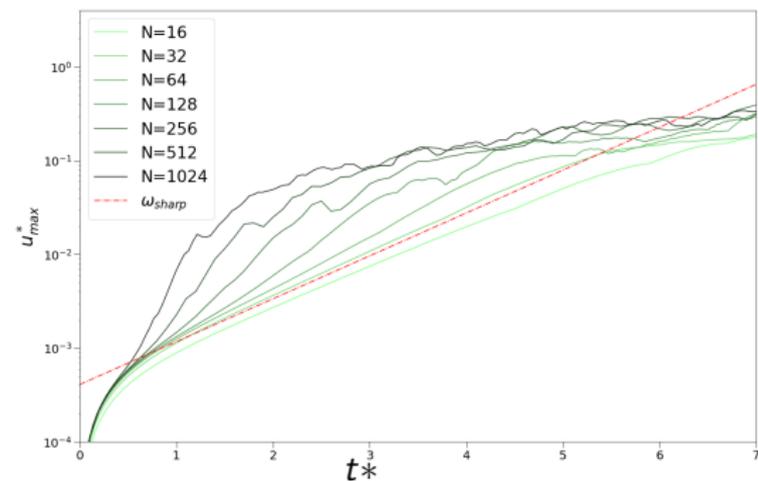
$N = 16$

$N = 64$

$N = 512$

# Simulation of the Classical One Fluid Model

►  $R = 0.7$



Questions:

- Non linear regime?
- Kelvin Helmholtz instability?
- Numerical Noise?

# Linear Stability Study:

Main goals:

- ▶ Analytical Analysis
- ▶ Numerical Validation

## Fundamental Equations For The Problem:

$$\frac{\omega^{Visc,Diff}}{\sqrt{gk}} = f \left( R = \frac{\rho_2}{\rho_1}, Re = \frac{\rho_1 g^{\frac{1}{2}}}{\mu_1 k^{\frac{3}{2}}}, M = \frac{\mu_1}{\mu_2}, We = \frac{\rho_1 g}{\sigma k^2}, \Delta k \right)$$

Simplified problem ( $\mu_1 = \mu_2 = \mu$ ):

$$\frac{\omega^{Visc,Diff}}{\sqrt{gk}} = f \left( R = \frac{\rho_2}{\rho_1}, Re, We, \Delta k \right)$$

$$\nabla \cdot \bar{\mathbf{u}} = 0$$

$$\bar{\rho} \left( \frac{\partial \bar{\mathbf{u}}}{\partial t} + \bar{\mathbf{u}} \nabla \bar{\mathbf{u}} \right) = -\nabla \bar{p} + \bar{\rho} \mathbf{g} + \bar{\mu} \Delta \bar{\mathbf{u}} + \sigma \kappa \nabla f$$

$$\frac{\partial d}{\partial t} + \bar{\mathbf{u}} \cdot \nabla d = 0$$

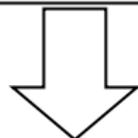
$d$  = distance to interface:

$$f = \begin{cases} 1 & d \geq \frac{\Delta}{2} \\ \frac{d}{\Delta} + \frac{1}{2} & -\frac{\Delta}{2} \leq d \leq \frac{\Delta}{2} \\ 0 & d \leq -\frac{\Delta}{2} \end{cases}$$

And  $f$  = fraction field

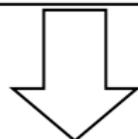
# Numerical Method for the Interface Diffusion

*The true interface is tracked  
with  
Volume Of Fluid Method*



*Computation of the distance to the interface  
with an iterative method (For each cell)*

*Initial signed distance field*



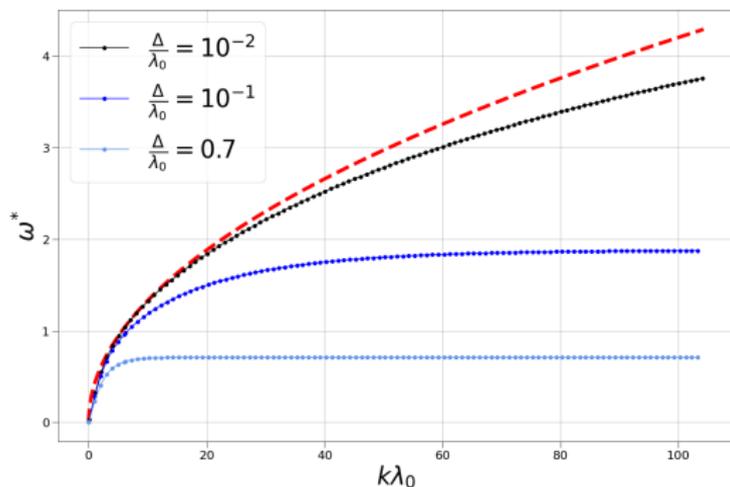
*Advection of this distance as a tracer + Relaxation toward the interface*

# Theoretical Results for the Inviscid with no Surface Tension Problem (FILTRED Regime)

$$\lim_{k \rightarrow \infty} \omega_{sharp}^2 = \infty$$

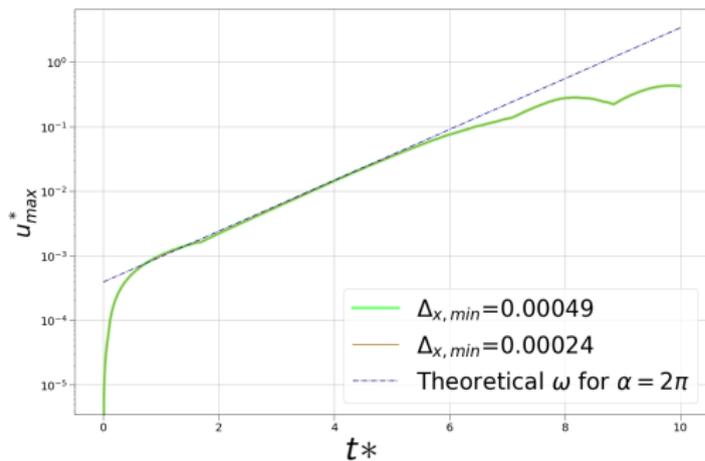
$$\lim_{\Delta k \rightarrow \infty} \omega_{Diff}^2 = 2 \frac{1 - R g}{1 + R \Delta} = \frac{2\omega_{sharp}^2}{k\Delta}$$

$$\lim_{k\Delta \rightarrow 0} \omega_{Diff} = \omega_{Sharp}$$



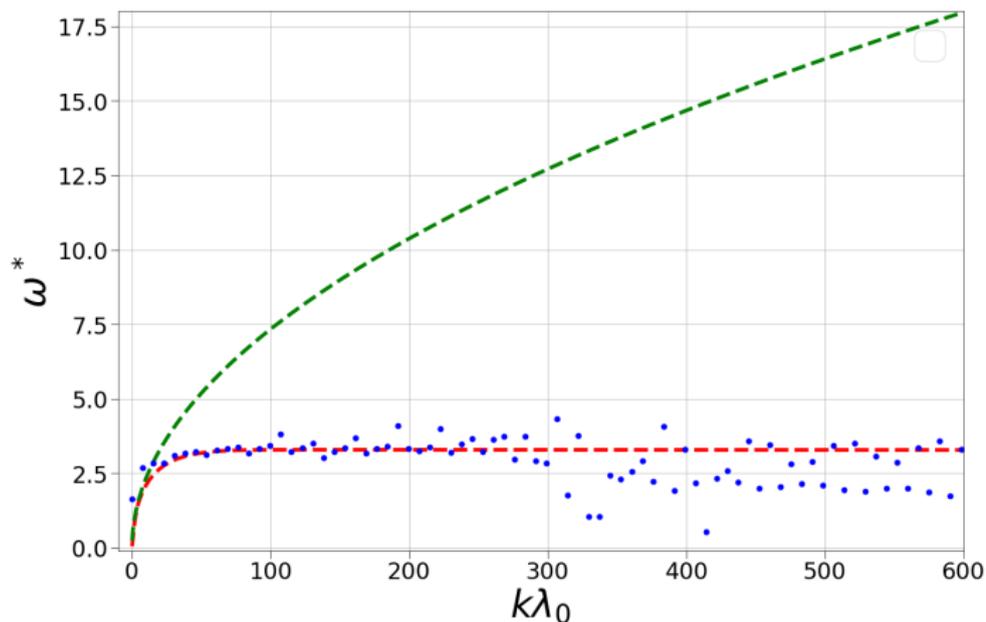
# Simulation of the Inviscid with no Surface Tension Problem

▶  $\frac{\Delta}{\lambda_0} = 0.2$  and  $R = 0.7$



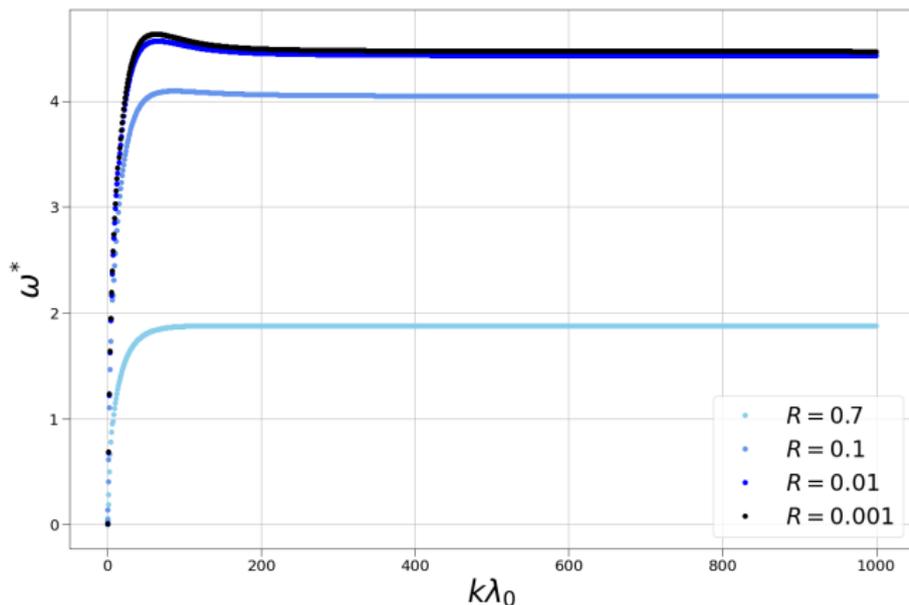
# Simulation of the Inviscid with no Surface Tension Problem

- ▶  $\frac{\Delta}{\lambda_0} = 0.1$  and,  $R = 0.3$



# Theoretical Results for the Inviscid with no Surface Tension Problem (Monotonicity)

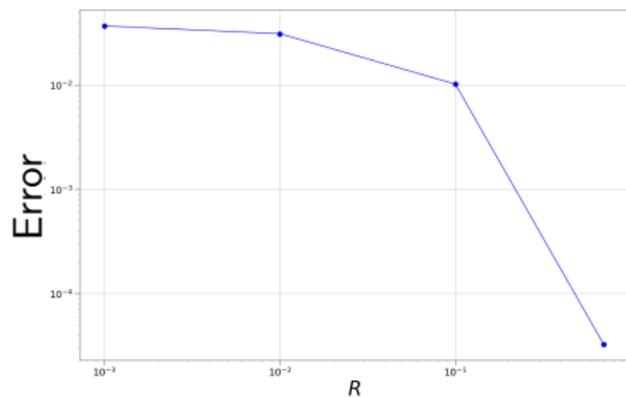
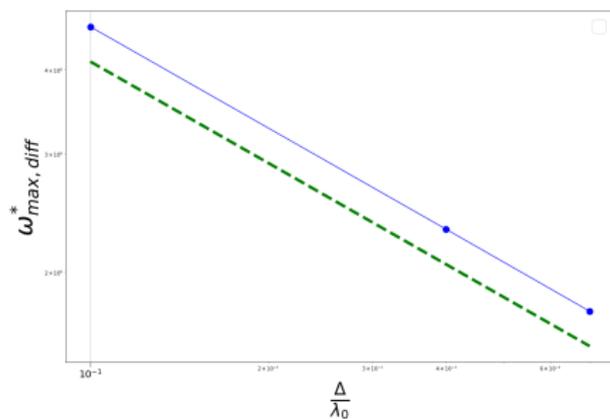
- ▶  $\omega^*(k\lambda_0)$  not monotonic



## Evolution of $\omega_{max}^*$ :

▶  $\omega_{max,diff} \sim \mathcal{O}\left(\Delta^{-\frac{1}{2}}\right)$

▶  $\omega_{max,diff} \approx \mathcal{O}\left(A_t^{\frac{1}{2}}\right)$

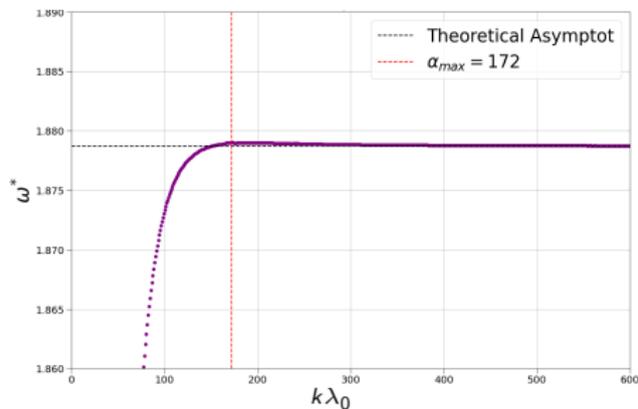
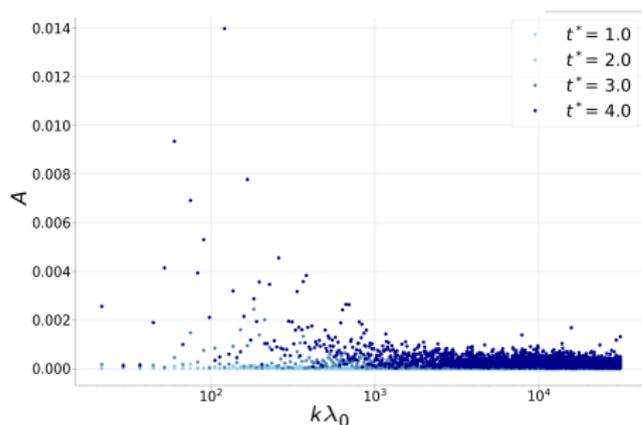


# Simulation of the Inviscid with no Surface Tension Problem

▶  $R=0.7$

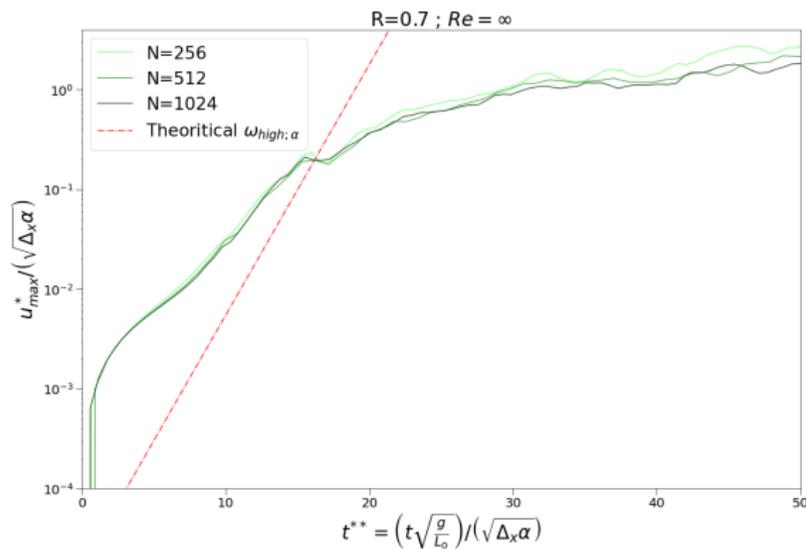
▶  $\frac{\Delta}{\lambda_0} = 0.02$

Numerical  $k_{max} \approx$  Theoretical  $k_{max} = 172$



# Back to the Classical Volume Of Fluid Method

►  $\frac{\Delta x}{\lambda_0} = \frac{1}{N}$  and  $R = 0.7$

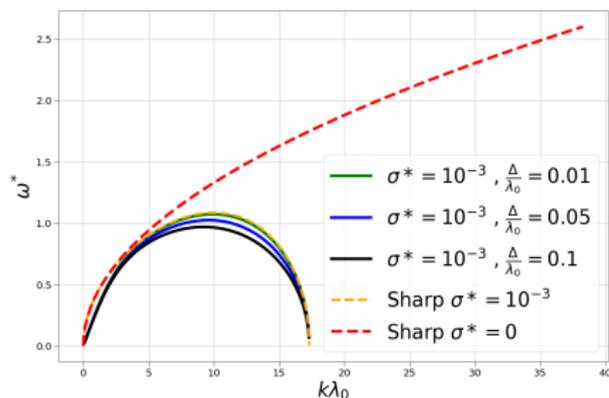


# What's next?

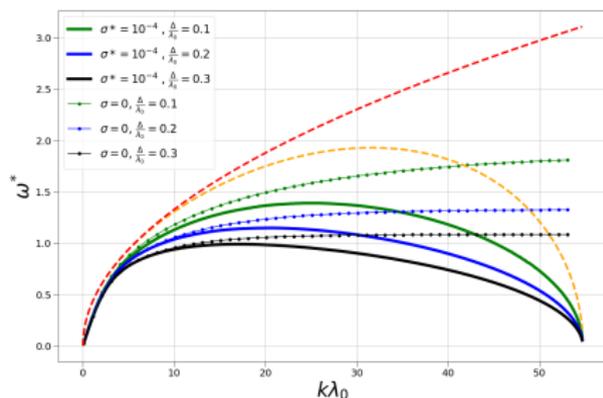
- ▶ What if we add some physical characteristic lengths to the system?

# Theoretical Results With Surface Tension:

## Regime 1:DNS Regime



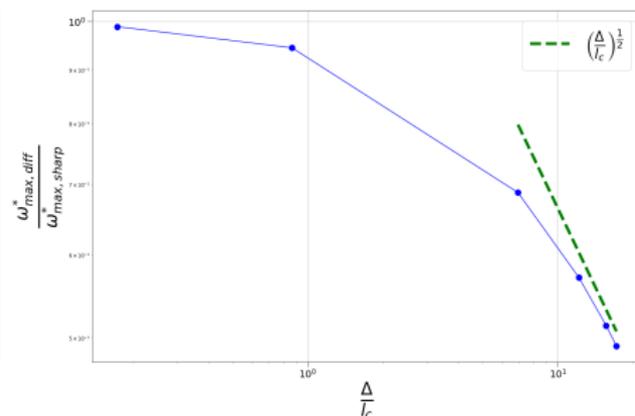
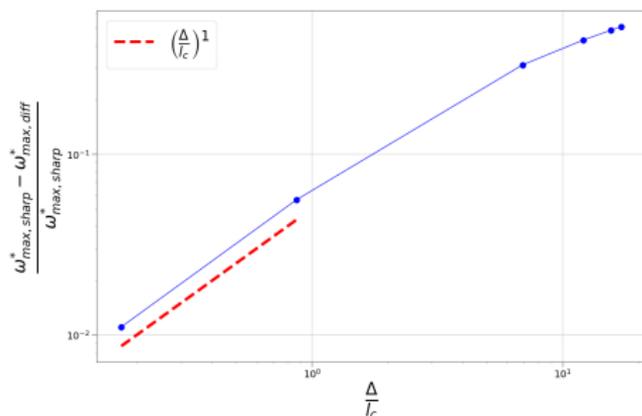
## Regime 2:FILTERED Regime



# Theoretical Results With Surface Tension:

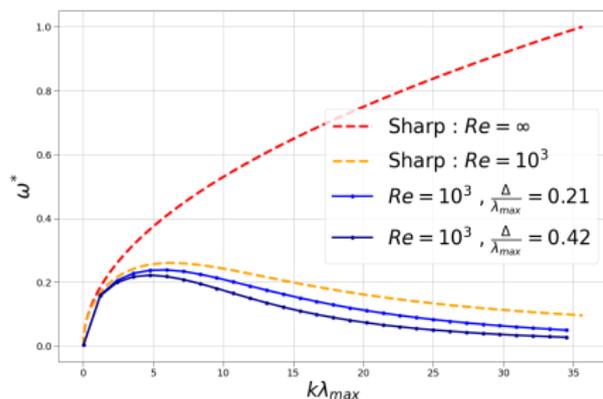
$$l_c = \sqrt{\frac{\sigma}{(\rho_1 - \rho_2)g}}$$

$\frac{\Delta}{l_c} \leq 1$  to achieve the DNS Regime

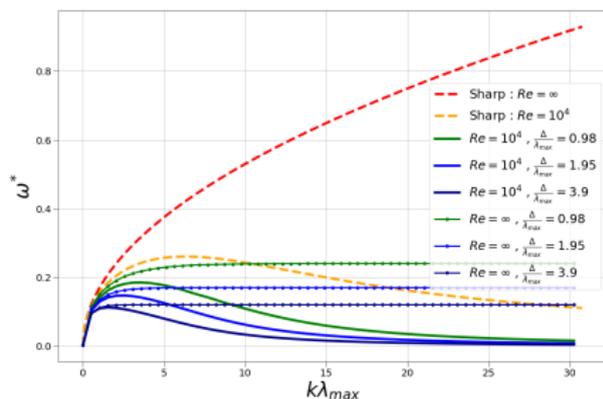


# Theoretical Results With Viscosity:

## Regime 1:DNS Regime



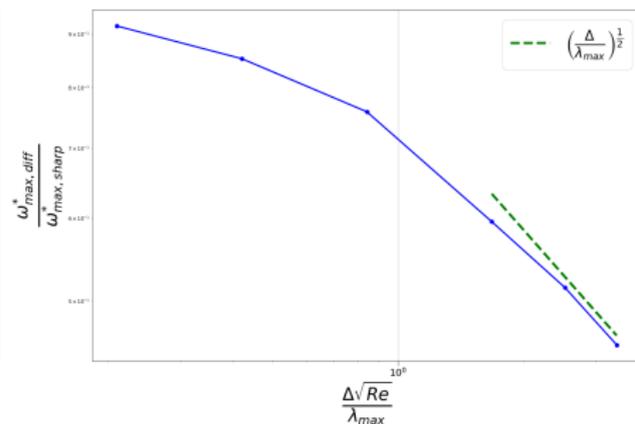
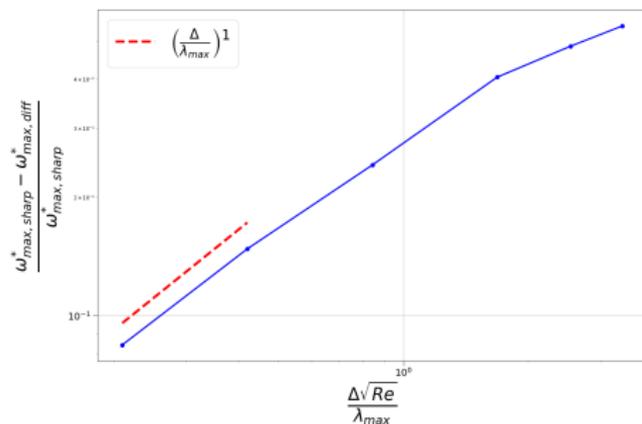
## Regime 2:FILTERED Regime



# Theoretical Results With Surface Tension:

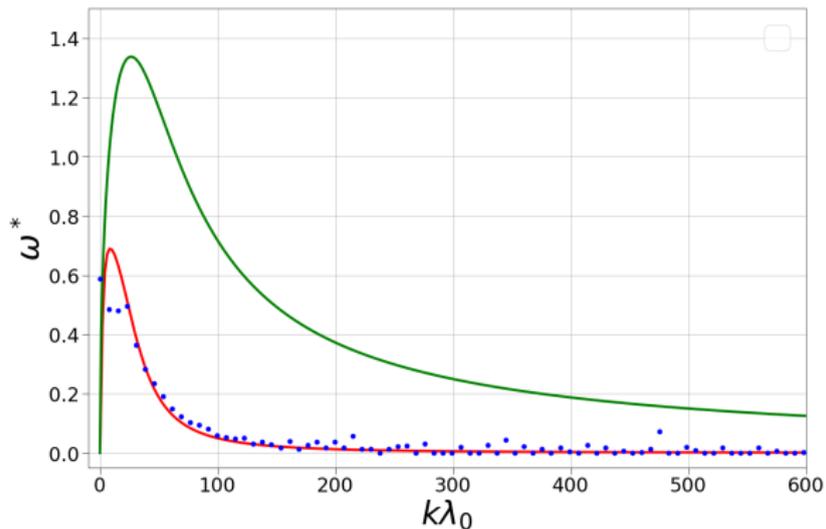
$$l_\nu = \frac{1}{\sqrt{Re}}$$

$\frac{\Delta}{l_\nu} \leq 1$  to achieve the DNS Regime

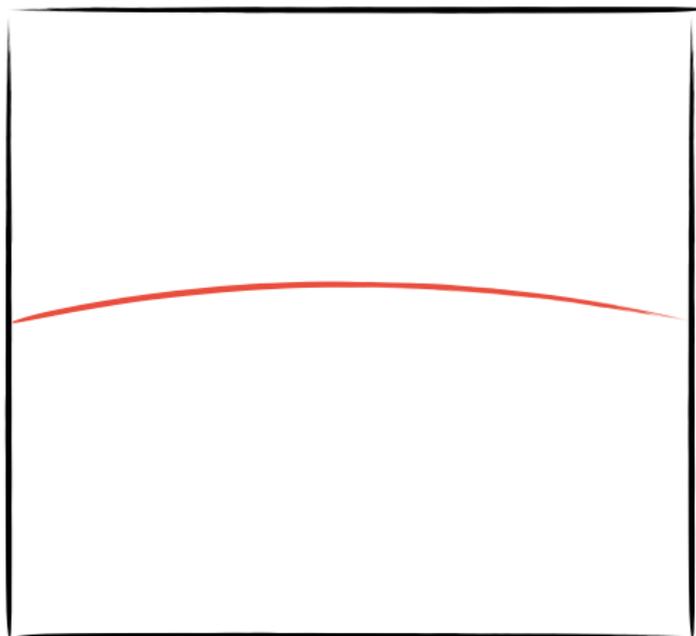


## Numerical Validation for the Viscous Case :

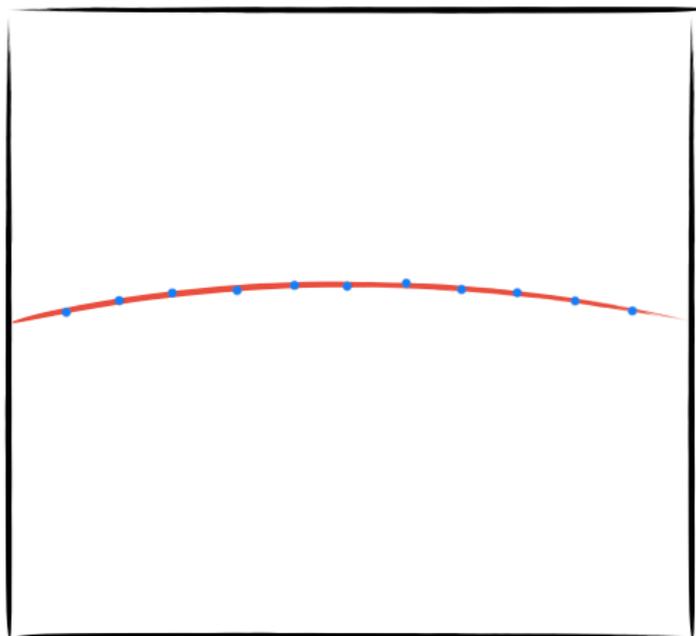
- ▶  $\frac{\Delta}{\lambda_0} = 0.6$
- ▶  $R=0.7$
- ▶  $Re=1000$
- ▶  $l_c = 0$



To summarize:

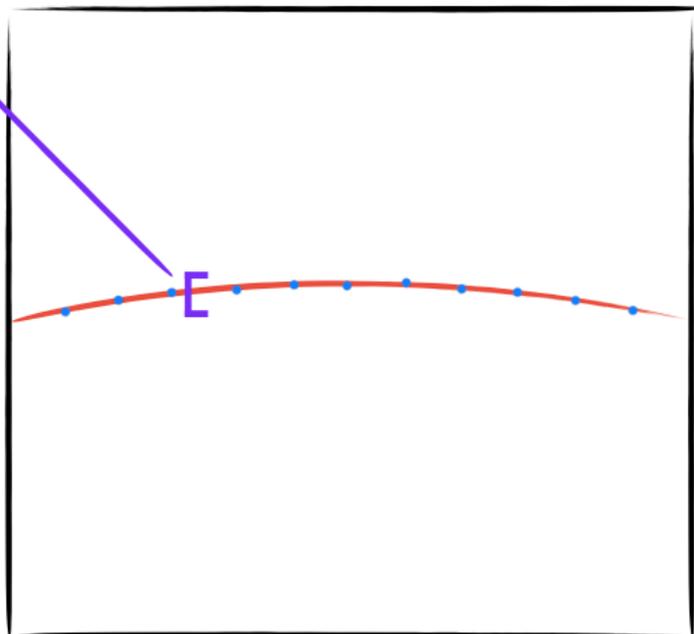


To summarize:

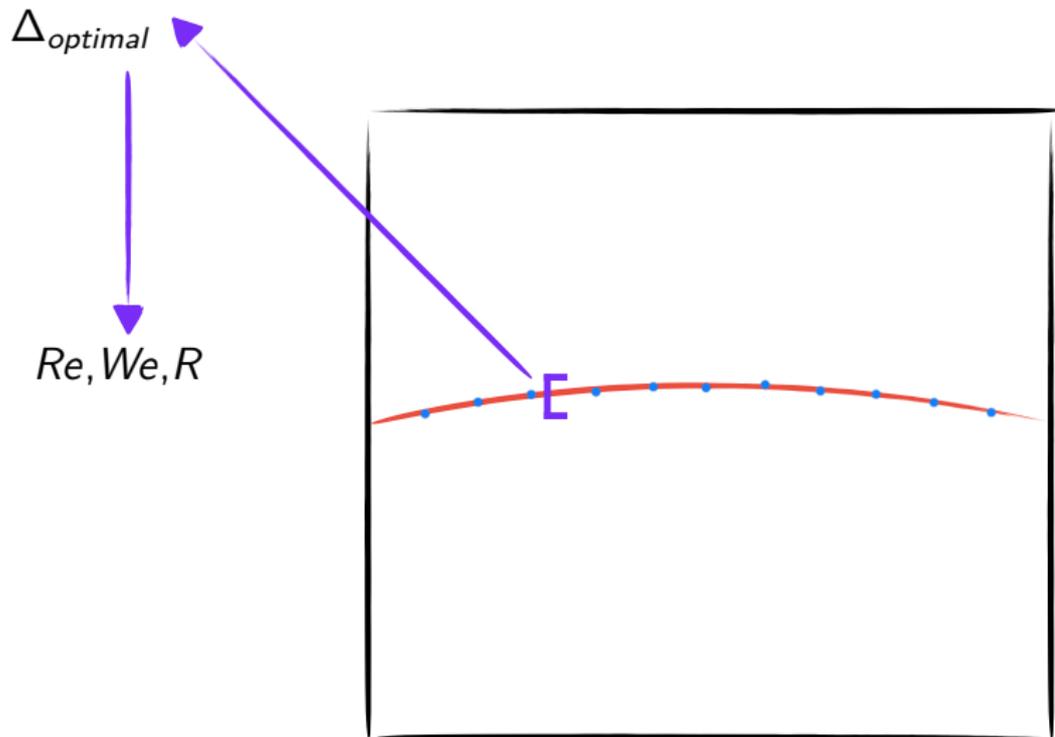


To summarize:

$\Delta_{optimal}$



To summarize:



# To Conclude

- ▶ Two important regimes:
- ▶ One governed by the regularization errors:  $\frac{l_c}{\Delta} < 1$  &  $\frac{l_v}{\Delta} < 1$
- ▶ One physical:  $\frac{l_c}{\Delta} > 1 \vee \frac{l_v}{\Delta} > 1$

Conclusion: When we satisfy the last criterion VoF Works!

Thank you!

Questions?